## Micro processor programmer controller (For 616) MY106P/MY406P/MY506P/MY706P/MY906P/MY606P INSTRUCTION MANUAL

Carefully readall the instructions in this manual. Please place this manual in a convenient location for easy reference.

### Specification

• MY06P series instrument: 4 big LED display, 0-100%LED bar display,

Accuracy: (Max $\pm$ 0.2% fus or  $\pm$ 1) $\leqslant$  $\pm$ 1 digit

RTD or TC input, the maximum resolution is 0.1 degree. Analog input ,the maximum resolution is 0.001 degree. Auto/Manual operation function,

- 4 patterns program can be used, 8 segments per pattern.
- Also can belinked together as 32 segments in ramp/soak program
- Output limited in every segment.
- System timer unit "hour"or "minute"or "second"
- Segment end alarm, Program run alarm, Program end alarm
- Power failure option
- SV waiting PV function
- Master and slave communication
- RS-485 communication Modbus-RTU
- PID control: As usual, controllers have PID control before leaving factory, with Autotuning function.
- Clients can set TC, RTD by keyboard ,please set the input type coincide with the sensor, Check details of the manual"6.3"parameter INP1, If need analog signal inputs, please specified when order. (Except 0-20mV or 0-50mV input)
- ON/OFF Control: Set P=0.0, it will be changed as on/off control. Check manual"6.1 parameter P" and "9.cotrol action instruction". Position difference is HYS. when heating :PV>SV, OUTstop, when PV<SV-HYS, OUT start, fitting forOUT1. When Cooling: PV>SV+HYS, output start, when PV<SV, output stop</li>
- when PID Control, we suggest adopt the Autotuning to improve the control effect. Check"8.Autotuning"

# 1. PRODUCT CHECK

MODELMY106P ( $48mmX48mm$ ) MY406P ( $48mmX96mm$ ) MY406P ( $48mmX96mm$ ) MY506P ( $96mmX48mm$ ) MY706P ( $72mmX72mm$ ) MY906P ( $96mmX96mm$ ) MY606P ( $160mmX80mm$ )CODECODECODECODEControl action N: No action F: ReversePID action (for Heating)D: Direct PID action (for cooling) P: Input type, (3) Range code: See"11.INPUT RANGE TABLE" P: First control output [OUT1] N: No action M: Relay contactN: No action M: Relay contactM: Relay contactV: Voltage pulse(for SSR) 2: Current(DC0~20mA)S: 0~5VDC6: 0~10VDC 7: 1~5VDC		
$\begin{array}{c} MY406P(48mmX96mm)\\ MODEL(Size: wideXhigh) & MY506P(96mmX48mm)\\ MY706P(72mmX72mm)\\ MY906P(96mmX96mm)\\ MY606P(160mmX80mm)\\ \hline \\ CODE\\ \hline \\ \hline \\ \bigcirc $	MODEL	MY106P (48mmX48mm)
$\begin{array}{c} \text{WY706P} (\text{72mmX72mm}) \\ \text{WY706P} (\text{96mmX96mm}) \\ \text{WY606P} (\text{160mmX80mm}) \\ \text{WY606P} (\text{160mmX80mm}) \\ \hline \\ \text{CODE} \\ \hline \\ $	MODEL (Size: wideXhigh)	MY406P (48mmX96mm) MY506P (96mmX48mm)
$\begin{array}{c} MY906P(96mmX96\mathsf{mm})\\ MY606P(160mmX80\mathsf{mm})\\ \hline\\ CODE\\ \hline\\ \hline\\ \bigcirc $		MY706P (72mmX72mm)
$\begin{array}{c} \text{WY606P} (160 \text{mmX80mm}) \\ \hline \\ \text{CODE} \\ \hline \\ $		MY906P (96mmX96mm)
CODE $\Box$		MY606P (160mmX80mm)
Image: Constraint of the second stress of	CODE	
①       ②       ③       ④       ⑤       ⑦       ⑧       ⑨       ①       (11)       (12)       (13)       (14)       (15)         I) Control action       N: No action       N: No action       D: Direct PID action (for cooling)       D: Direct PID action (for cooling)         2) Input type, (3) Range code: See"11.INPUT RANGE TABLE"       4) First control output [OUT1]       N: No action         M: Relay contact       V: Voltage pulse(for SSR)       2: Current(DC0~20mA)       8: Current(DC4 ~ 20 mA)       5: 0~5VDC       6: 0~10VDC         7: 1~5VDC       T:Triac single phasezero crossing contact       T:Triac single phasezero       T.Triac single phasezero		I-000-0/0/0/0
I) Control action         N: No action         F: ReversePID action (for Heating)       D: Direct PID action (for cooling)         I) Input type, (3) Range code: See"11.INPUT RANGE TABLE"         I) First control output [OUT1]         N: No action         M: Relay contact       V: Voltage pulse(for SSR)         2: Current(DC0~20mA)       8: Current(DC4 ~ 20 mA)         5: 0~5VDC       6: 0~10VDC         7: 1~5VDC       T:Triac single phasezero crossing contained		<b>(9) (11) (12) (13) (14) (15)</b>
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<ul> <li>First control output [OUT1]</li> <li>N: No action</li> <li>M: Relay contact</li> <li>2: Current(DC0~20mA)</li> <li>5: 0~5VDC</li> <li>7: 1~5VDC</li> <li>7: 1~5VDC</li> <li>V: Voltage pulse(for SSR)</li> <li>8: Current(DC4 ~ 20mA)</li> <li>6: 0~10VDC</li> <li>7: 1~5VDC</li> <li>T:Triac single phasezero crossing cont</li> </ul>	(2) Input type, (3) Range code: Se	e"11.INPUT RANGE TABLE"
N: No actionM: Relay contactV: Voltage pulse(for SSR)2: Current(DC0~20mA)8: Current(DC4 ~ 20mA)5: 0~5VDC6: 0~10VDC7: 1~5VDCT:Triac single phasezero crossing contact	(4) First controloutput [OUT1]	
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2: Current(DC0~20mA)8: Current(DC4~20mA)5: 0~5VDC6: 0~10VDC7: 1~5VDCT:Triac single phasezero crossing control	M: Relay contact	V: Voltage pulse(for SSR)
5: 0~5VDC6: 0~10VDC7: 1~5VDCT:Triac single phasezero crossing cont	2: Current(DC0~20mA)	8:Current(DC4 ~ 20mA)
7: 1~5VDC T:Triac single phasezero crossing cont	5: 0~5VDC	6:0~10VDC
	7: 1~5VDC	T:Triac single phasezero crossing cont

H:Unidirectional triac singlephase zero crossingcontrol K:Triac 3 phase zero crossingcontrol

- L:Unidirectional triac 3 phase zero crossing control
- C:Triac single phase angle control
- Q:Unidirectional single phase angle control
- S:Triac 3 phase angle control
- D:Unidirectional 3 phase angle control

#### Remark code:N

- (6) Alarm 1[AL1] (7) Alarm 2[AL2] (8) Alarm 3[AL3]See "6.3.1 alarm mode"
  - A: Deviation high alarm B: Deviation low alarm
- J : Process low alarm K: Process high alarm with hold action

H: Process high alarm

L: Process low alarm with hold action

2: Segment end alarm (Program)

- C: Deviation high/low alarm
- D: Deviation band alarm
- E: Deviation high alarm with hold action
- ${\rm G:} \ \ {\rm Deviation \ high/low \ alarm \ with \ hold \ action } \ \ {\rm 4: \ Program \ end \ alarm \ (Program)}$
- 9. Remark code: N
- (i). Communication
   (ii). No Communication
   (iii). Since the second se
- N:No transmission

   C: PV transmission (4-20mA)

   P: PV transmission (0-5V)

   R: SV transmission (0-5V)

   Q: PV transmission (0-10V)

   S: SV transmission (0-10V)

   Y: Programmable system timer unit
- I2. Programmable system timeruni N: No program

H: Hour(0.0~999.9hr) M: Minute(0.0~999.9Min) S: Second (0-9999s)

- (13). Program start up mode N:No program R:Start by pressing key A:Auto start when power on
- (14). Program starts and Power failure N: No Programmable
  - A: Program starts from "0", No power failure option
  - B: Program starts from "0", With power failure option
  - C: Program starts from "PV", No power failure option
  - D: Program starts from "PV", With power failure option
- (15). Program repeat select

N: No program A:Program not repeat B:Program repeat

# 2. MOUNTING SIZE



# 3. WIRING



10 20 30 40 50 60 70 80 90 100

10 20 30 40 50 60 70 80 90 10

# 5. SETTING

## 5.1 Calling up procedure of each mode



## 5.2 Setting parameter value(AL1)

Example: Following is an example of set value(AL1) to 200°C (2)Shift of the digit brightly lit (4) Set value entry (1)Set to the Al1 setting mode (3) Numeric value change RI 2 RL RL RL 0000 0000 0200 200 sv sv sv sv In the normal display Press the shift key **4** to shift the digit which lights brightly up to the hundreds After finishing the setting, Press Press the UP key 
to set "2"
Pressing the UP key increase modePress 4 key to enter the SV setting the SET key to the next parame numerals, and pressing the mode. The digit which diahts flashingis settable numera \*In any time you can press A/M key to save value and exit to PV/SV mode

# 6. LEVEL

#### 6.1 Level 1 (Program Level) 6.1.1 Press the SETkey to level1: Ħ The following parameter symbols are displayed one by one every time the SET key is pressed. 25 Normal display P٧ \*\*The following only for programmablecotroller SEG Program Segment display (Pattern\_Segment) SUIL Only checking Press SET key Rate Slave settingvalue rai Range 0-9999 Only display in slave controller Press SET key Slave settingvalue rate Range 0-9999 Program running timer display Only for checking t-H : Indicate hour unit t-M: Indicate minute unit E -H0000 -S: Indicate second unit At Autotuning Press SET key <u>RE</u> PLCK (Program lock) =0 Not allow to nextparameter =1 Only allow to displaynext parameter, not allow tomodify =2 Allow to modifynext parameters PL 00 Е Press SET key 0002 AL1 Set the alarm value foralarm 1 Alarm differential gap=AH1 or setting segment number of segment end alarm function PLCK=2 Press SET key Rt 1 \*\*\* PLNK (Program pattern select) =1,select No.1 group (8 segments) =2,select No.2 group (8 segments)) =3,select No.3 group (8 segments) =5,select No.3 ergoup (8 segments) =5,select No.3 +4 group (16 segments) =7 select No.3 +4 group (16 segments) 0 PLNY s٧ Press SET key 0001 AL2 Set the alarm value foralarm 2. Alarm differential gap=AH2 or setting segment number of segment end alarm function RL Press SET key sv =7,select No.1+2+3 group (24 segments) =8,select No.1+2+3+4 group (32 segments Press SET key PSEL PSEL , select settinggroup AL3 Set the alarm value foralarm 3. Alarm differential gap=AH3 or setting segment number of segment end alarm function Enter No.1 group parameter Enter No.2 group parameter Enter No.3 group parameter Enter No.4 group parameter ΡV RL. 3 0001 0 sv Press SET key PSEL DODY PSEL 1000 / IP S E PSE UAd URJ P٧ Device address checking for RS-485 communication nnc sv 1 Press SET key To next page





MY06P-616-E1

## 6.2 The example of program procedure

Assume the temperature profile is as below (Total 5 segments, and the output limit of segment 4 is 80%) Unit of timer: hour



### 6.3 Program END

4

If program procedure is less than 8 segments, please set the next segment's "ot\_.\_" of the last segment to "0.0". Program will be end at this segment. In the above example, program only need 5 segment, please set "ot1.6" to 0.0%, the program will be end when program run finish at segment 5.

### 6.4 Program JUMP to next segment

In program procedure, if some segment will be not used, you can set "tr\_.\_" to 0 or 0.0. Such when program running in this segment, program will auto jump to next segment running.

## 6.2 Level 2

Sy

Press the SETkeyfor 3 seconds to level 2 The one

l he following one every tir	g parametersyr ne theSET key	nbols are dis ispressed.	played	0neby
Symbol	Name	Range	1#	Description
Ρ!	Proportional band for out1	0.0~200.0	20.0	Proportional band in PID with unit °C for OUT1 P1=0.0, ON/OFF control forouput1
, 1	Integral time	0-3600sec	210	Set the time of integral action to eliminate
d (	Derivative time	0-3600sec	30	Set the time of derivative action to improve control stability by preparing for output changes.
REGL	Auto tuning offset value (AtVL)	0-199	0	Set ATVLto prevent overshoot occurred during autotuning process.
EYE I	Proportioning	0 to 999sec	20	Proportioning cycle time for PID control
HYS I	Control Hysteresis For out1	0.0 to 100.0	2.0	Control out differential gap=HYS1 For out1 output. Only for ON/OFF action when P1=0.0
r5E (	Proportional reset For out1	-30 to 30	-5.0	Proportional reset for overshootprotection only for out1 output. (Auto setting after autotuning)
OPL	Output1 limit (Low)	0.0 to 100.0%	0.0	Output manipulated variable lowest limit For out1 output.
0PH	Output1 limit (High)	0.0 to 100.0%	100.0	Output manipulated variable highest limit For out1 output.
LER	Set data lock	0000-0255	0000	LCK=0000:Allow to modify any parameter and SV LCK=0001:Only allow to modify SV LCK=0010:Only allow to modify SV and Level1 LCK=0011:Not allow to modify any parameter and SV LCK=0101:Allow to setting Level3

#### 6.3 Level3

6.3.1Go to level 3: 1, Press the SETkey for 5 seconds to PID level, then change LCKto 0101.



2,Press the **4** key while pressing the **SET** key for 3s to Level3

The following parameter symbols are displayed oneby one every time the SET key is pressed.

	Main input ty Setting L' / Input K Range 4000 °C Setting S Range 1000 °C 400 Note: AN4,AN: without co Decimal point 	K         F           K         1300 °C         30           L         r         1           T         R         0.0 °C         1700 °C           3         input typesalibration         0,1,2,3           -1999 to 99999         -1999 to 99999           0,1,2         -1999 to 99999	E / E 0.0 °C B 800 °C 4 e can n (Custo 0 0 400	E E 600 °C 	L J J 400.0 °C R[7]3 R] 400.0 °C R[7]3 R] 0-10VDC 0-5VDC 0-50m 0-5	J Z J 800 °C 72 AN omv 0-20m keyboar ear anal- etting li	Image: Physical system           Image: Physitem           Image: Physical system </th <th>U           Wu3_Re25           000 °C           I         PE2           0         Pt100           10 °C         200-800 °C           use of         input</th>	U           Wu3_Re25           000 °C           I         PE2           0         Pt100           10 °C         200-800 °C           use of         input		
USPL	Main input ty Setting <u>L'</u> / Input <u>K</u> Range 400.0 °C Setting <u>5</u> Range 1000 °C 400 Note: AN4,AN: without co Decimal point 	ype select <u> <u> </u> <u> <u> </u> <u> </u></u></u>	E / E 0.0 °C B 800 °C 4 e can n .(Custo 0 0 400	E 2 600 °C 	<u>J</u> 1 <u>J</u> 400.0 °C <u>RI73</u> <u>RI</u> 0-10VDC 0-55VDC 0-20mA 0-50 0-20mA 0-50 0-5	J 2 J 800 °C 72 RT 0mV 0-20m keyboar earanal ettingli	Image: 100 million         Image:	Image: wus_Re25           Wus_Re25           000 °C           I         PE2           0         Pt100           10 °C         200-800 °C           uuse of         Image: wuse of		
	Annut K Range 4000 °C Setting 5 Range 1000 °C Note: AN4,AN without c Decimal point .ow setting miter ligh setting miter Display scale	E         C           1300 °C         30           L         r           T         R           0.0 °C         1700 °C           3 input type           calibration           0.1,2,3           -1999 to 9999           0.1,2,3	E i E 0.0 °C B 800 °C 4 4 e can n (Custo 0 0 400	<u>E</u> 600 °C 7/74 / -10VDC -5VDC -20mA 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1 Units Set Low Set Low	<u>J</u> <u>J</u> <u>400.0 °C</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u> <u>RITJ</u>	<u>j</u> J 800 °C 72 AN 0mV 0-20m keyboar earanal ettingli	// N 1300 °C / PL / PL10 .199.9-200 d, beca og type miter	L           Wu3_Re25           2000 °C           1         PE2           0         Pt100           10 °C         -200-800 °C           use of		
dp D LSPL	Range 400.0 °C Setting <u>5</u> nput <u>5</u> Range 1600 °C 400 Note: AN4,AN1 without c Decimal point Low setting imiter ligh setting miter Display scale	K         300         °C         30           1300         °C         30         30         30           L         r         R         70          70          70 <th>E 0.0 °C B 800 °C 4 Custo 0 400</th> <th>e 600 °C </th> <th>J           400.0 °C           RIT3         RI           0.10VDC         0.5           0.20MA         0.5           ting by k           hade)         , 2, 3           y for Line           lower s           er point</th> <th>800 °C 72 RT 00mV 0-20m keyboar earanal ettingli</th> <th>N 1300 °C / PL v Pt10 -199.9-200 d, beca</th> <th>WU3_K625           2000 °C           ·         /         PE2           0         Pt100           0.0 °C         -200-800 °C           use of</th>	E 0.0 °C B 800 °C 4 Custo 0 400	e 600 °C 	J           400.0 °C           RIT3         RI           0.10VDC         0.5           0.20MA         0.5           ting by k           hade)         , 2, 3           y for Line           lower s           er point	800 °C 72 RT 00mV 0-20m keyboar earanal ettingli	N 1300 °C / PL v Pt10 -199.9-200 d, beca	WU3_K625           2000 °C           ·         /         PE2           0         Pt100           0.0 °C         -200-800 °C           use of		
LSPL	Range 4000 c Setting <u>5</u> nput <u>5</u> Range 1000 °c 400 Note: AN4,AN: without c Decimal point .cow setting imiter ligh setting miter Display scale	I Store         I Store <thi store<="" th=""> <thi store<="" th=""> <thi< th=""><th>B         I           B         2           800 °C         4           e can n         (Custo           0         0           400         400</th><th>ot set Don 1 Don 2 Don 2 Don 2 Don 1 Don 1 D</th><th>AUC.U C AUT.J AI 0-10VDC 0-5VDC 0-5VDC 0-20MA 0-5 0-5VDC 0-5 0-5 0-5 0-5 0-5 0-5 0-5 0-5</th><th>omv 0-20m ceyboar earanal</th><th>/ PL V Pt10 .199.9-200 d, beca og type miter</th><th>2000 C           I         PE 2           0         Pt100           10 °C         -200-800 °C           use of        </th></thi<></thi></thi>	B         I           B         2           800 °C         4           e can n         (Custo           0         0           400         400	ot set Don 1 Don 2 Don 2 Don 2 Don 1 Don 1 D	AUC.U C AUT.J AI 0-10VDC 0-5VDC 0-5VDC 0-20MA 0-5 0-5VDC 0-5 0-5 0-5 0-5 0-5 0-5 0-5 0-5	omv 0-20m ceyboar earanal	/ PL V Pt10 .199.9-200 d, beca og type miter	2000 C           I         PE 2           0         Pt100           10 °C         -200-800 °C           use of		
LSPL	Setting 5 nput s Range 1600 °C 400 Note: AN4,AN: without c Decimal point .cow setting imiter ligh setting miter Display scale	L         r           T         R           0.0 °C         1700 °C           3 input type           calibration           0 ,1,2,3           -1999 to 9999           -1999 to 99999           0 ,1,2	<u>B</u> B B B C C B C C C C C C C C C C C C C	ot set 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1	ADJ AI 0.10VDC 0.5VDC 0.5VDC 0.5 0.20MA 0.5 0.5 0.5 0.5 0.5 0.5 0.5 0.5	omv 0-20m keyboar earanal	/ PL v Pt10 -199.9-200 d, beca og type	PE2           0         Pt100           0.0 °C         -200-800 °C           use of		
dP LSPL	nput s Range 1600 °C 400 Note: AN4,AN: without c Decimal point .ow setting imiter ligh setting miter Display scale	T         R           0.0 °C         1700 °C           3 input type           calibration           0 ,1,2,3           -1999 to 9999           -1999 to 9999           0 ,1,2	B 800 °C 4 e can n (Custo 0 400 400	ot set 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1 0, 1	ting by k nade) , 2,3 y for Ling lower s er point	ear anal	v <u>Pt10</u> -199.9-200 d, beca og type	0 Pt100 0.0 °C -200-800 °C use of input		
dP P LSPL L USPL	Ange 1600 °C 400 Jote: AN4, AN: without c Decimal point .ow setting imiter ligh setting miter Display scale	0.0 °C 1700 °C 1 3 input type alibration 0,1,2,3 -1999 to 9999 -1999 to 9999 0,1,2	800 °C 4 e can n .(Custo 0 0 400	ot set om - m 0, 1 Only Set Low	ting by k nade) , 2,3 y for Line lower s er point	earanal ettingli	d, beca	use of		
dP D LSPL L USPL H	Jote: AN4,AN. without c Decimal point .ow setting imiter digh setting miter Display scale	3 input type calibration 0 ,1,2,3 -1999 to 9999 -1999 to 9999 0 ,1,2	Custo 0 0 400	ot set om - m 0, 1 Only Set Low Set	ting by k nade) , 2,3 y for Line lower s er point	earanal eatingli	d, beca og type	use of input		
dP D LSPL    USPL	Decimal point ow setting imiter ligh setting miter Display scale	0 ,1,2,3 -1999 to 9999 -1999 to 9999 0 ,1,2	0 0 400	0, 1 Only Set Low	, 2,3 y for Line lower s er point	ear anal etting li	og type miter	input		
LSPL    USPL	ow setting imiter ligh setting miter Display scale	-1999 to 9999 -1999 to 9999 0 ,1,2	0 400	Set Low Set	lower s	ettingli	mitor			
	imiter ligh setting miter Display scale	-1999 to 9999 0 ,1,2	400	Low Set	er point	<u> </u>	mitter			
USPL 🖁	ligh setting miter Display scale	-1999 to 9999 0 ,1,2	400	Set		of trans	mission	or remove SV		
וון <i>ב ייב</i> ים	miter Display scale	0 ,1,2	1	LUICH	high se	ttinglin	niter			
_	Nsplay scale	0,1,2		HIG	Higher point of transmission or remove SV					
	N/ hine		0	0: 0 2: v	vithout	ade, 1: scale (	for lin	enheit ear analog)		
<i>P'_'0</i> 5 P	v DiaS	-199to 199	Sen: valu	Sensor correction is madeby adding bias value to measured value(PV).						
	PV follow-up	0 to 60 55		PV variable-value control,						
/ _/ _ P	V input filter			U-30: 101 general, 31-60:101 ennanced						
	owest value of V display	-199~9999	0	Such as 4-20mA input.						
RNH I P	ighest value of V display	-1999~9999	2000	Such as 4-20mA input.				ar analog input		
ALd / A	larm1 mode	00 to 16	11	Select the type ofalarm1 See(**ALARM TYPE TABLE)						
FIH 1	larm1 ifferential gap	0.0 to 100.0	0.4	Alarn	n1 differen	itial gap se	etting			
ALd2 A	larm2 mode	00 to 16	10	Sele See	ct the ty (**ALARI	pe ofala M TYPE	rm2 TABLE)			
RHZ di	larm2 ifferential gap	0.0 to 100.0	0.4	Alarm2 differential gap setting						
AL d 3 A	larm3 mode	00 to 16	10	Select the type of alarm3						
	larm3 ifferential gap	0.0 to 100.0	0.4	Alarm3 differential gap setting						
<u> </u>	Control action	0 or 1	0	0: Reverse action (Heating) 1: Direct action (Cooling)			)			
	Lt Delay time of egment end alarm	0-9999 s	0	=0: alarm no delay remove =Others value : Ondelay time alarm remove AL1 value: alarm segment No.set				rm remove No.set		
ūR ie 🖁	<sub>Vait</sub> SV wait PV	0.0-100.0		Use =0:	d for prog Not wait.	ram towai =(	it continu Othersval	ed operation ue: Wait value		
	PUNt Program system time unit	0,1,2	0	0: H 1: M 2: S	lour (0.0 linute (0 econd (	)~999.9 ).0~999 0-9999	hour) .9 minut second)	te)		

#### Symbol 1# Description Name Range PrF ProgramSV Initial value 0: Program running from "0" PEF 0,1 1 1: Program running from "PV" value Device address 0-127 1 Communication device address setting. ЫПО setting 0,1,2,3 2 Band-rate BAUd =0: 2.4K, =2: 9.6K, =1: 4.8K, =3: 19.2K BRUJ setting \*\*ALARM TYPE TABLE (ALd\_=00~18) 00: No alarmoutput 01: Deviation highalarm with holdaction 10: No alarmoutput 11: Deviation high alarm 12: Deviation low alarm 02: Deviation low alarm with hold action 13: Deviation high/lowalarm 03: Deviation high/low alarm with hold action 04: Deviation band alarm with hold action 14: Deviation band alarm 15: Process high alarm 05: Process high alarm with hold action 16: Process low alarm 06: Process lowalarm with hold action 17: Program run alarm\*\* 07 : Program segmnet end alarm\*\*

#### 6.3.2 Alarm mode specification

18: Program endalarm\*\*



#### 6.3.2 Alarm mode specification

ALd	Sne				
	Opc	cification (Exan	nple for alrm1)		
05	Process high alarm with	AH1 Alarm ON	→ 		
	LOW	$\triangle$ AL1	пюп		
06	Process low alarm with	hold action			
	LOW	$\Delta$ AL1	HIGH		
07	Program segmnet end alarm**				
17	Program run alarm**				
18	Program end alarm**				
	05 06 07 17 18	05 Process low alarm with 06 Process low alarm with 06 LOW 07 Program segmnet end 17 Program run alarm** 18 Program end alarm**	05 05 COW COW COW COW COW COW COW COW		

NOTE:

With hold action: When Hod action is ON, the alarm action is suppressed at start-up until the measured value enters the non-alarm range.

#### 6.3.3 About program alarm specification

Segment end alarm\*\*: There are 3alarm parameters "ALd1、ALd2、ALd3" can be used for segment end alarm. The corresponding parameters arALT, AL2, AL3, When AL1, AL2AL3–0.32 (imeans that segment end alar mill act. The corresponding parameters arALT, AL2, AL3, When AL1, AL2AL3–0.32 (imeans that segment ends, alarm ends and alarm acts

Example: ALd1=07(Segment end alarm)

AL1=2 (It means when segment 2 end, AL1 relay will act) ) ALT=10 (It means the time of relay on is 10 seconds)

Program running alarm\*\*: Also there are 3alarm parameters (ALd1/2/3) whichcan be used for program run alarm If ALd1=17, Itmeans when the programis running, AL1relay will act.

Program end alarm\*\*: There are 3 alarmparameters (ALd1/2/3) which can be used for program end alarm. If ALd1=18, It means when the program end, AL1 relay will act.

6.4 Level4

6.4.1Go to level 4:

1, Press the SET key for 5 seconds to PID level, then change LCK to 0201.



#### 2, Press the 4 key while pressing the SET key for 3s to Level3

The following parameter symbols are displayed oneby one every time the SET key is pressed. 1# Factory set value

	1			
Symbol	Name	Range	1#	Description
EonF	ConF Communication configure	0,1,2	0	ConF=0: Disable communication ConF=1: RS-485 communication Modbus-RTU ConF=2: TTL communication (Master or slave)
Er5F	TrSF Transmission	0, 1	0	TrSF=0: PV transmission trSF=1: SV transmission
PErL	PCrL Program function configure	0, 1	1	PCrL=0: Setting controller for SLAVE PCrL=1: Setting congroller for 32 segment programmable controller or MASTER
oE /	Ot1 Analog output configure (DA)	0, 1	0	Ot1=0: Setting DA outputfor transmissionoutput Ot1=1: Setting DA outputfor PID control output
RUED	AUtO Configure AUTO/MANUL	0,1	0	AUTO=0: Disable Auto/manul Switching AUTO=1: Enable Auto/manul Switching
Р-ОП	PrON Program start up mode	0, 1, 2	0	PrON=0: Program start by start key pressing. PrON=1: Power failure option PrON=2: Program auto start when power on.
Р-ЕР	PrEP Program repeat action	0, 1	0	PrEP=0; Program do not repeat run when program is END. PrEP=1; Program repeat run when program is END.

## 7.MANUAL OPERATION

All instrument except MY106P with manual operation key (AM)

## Auto control mode

Example: Following is an example of manual setting to 70% output. Manual setting mode Manual control mode



MAN lamp is turns off in Auto control mode.



Press A/M key for 3 seconds to manual setting mode. In manual setting mode, MAN lamp light up, The digit which flashing is settable.

increase numerals and pressing the DOWN key decrease numerals. Press SET key after set value to 70.0.

Pressing the UP key

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MY906

(SFT (A/M)

\*\*In manual control mode ,press A/M key for 3 seconds to auto control mode. \*\*Power-on Manual function can be selected. Pko in level2 for initial output value. \*\*A/M key can also be used for SAVE and EXIT key.

## 8. AUTOTUNING

When controller's power are just on, it will be good to autotuning when the measured value is far lower than the set value



The autotuning target value is the first segment setting value

# 9.TTL Communication(Master & Slave)

9.1 Master : Programmable master controller with TTL communication. 9.2 Slave: Slave controller, SV value autosetting by master communication.



Note: All controller , please setting the same band-rate communication.



## **10.COMMUNICATION SPECIFICATION**

- (1) Communication protocol is Modbus-RTU, support 03 read command,06 or 10 write command
- (2) Communication mode: single-master RS485 asynchronous serial communication

baud rate: 2400, 4800, 9600, 19200(9600 baud rate is acquiesced) Byte date format:1 start bits,+8 data bits+No parity checking+1 Stop bits (3) Controllers support writing 36 data more.

(4) Controllers support reading 37 data more.

(5) Parameter address please see "MY06P series communication address list"

## **11. INPUT RANGE TABLE**

Input type		Code		Input type			Code	
	0.0 to 200.0 °C	2	D2		0.0	to 50.0 °C	P	06
K1	0.0 to 400.0 °C	2	D4	Pt1	0.0	to 100.0 °C	Р	07
	0 to 400 °C	κ	A4	(Pt100)	0.0	to 200.0 °C	Ρ	80
K2	0 to 600 °C	к	A6	( ,	-50.0	to 100.0 °C	Р	13
	0 to 1300 °C	K	B3		-199.	9 to +200.0 °C	P	02
E 1	0.0 to 200.0 °C	3	D2		0	to 100 C	D	A1
<b>L</b> 1	0.0 to 300.0 °C	3	D3		0	to 200 °C	D	A2
	0 to 200 °C	Е	A2	Pt2	0	to 400 °C	D	A4
E2	0 to 400 °C	Е	A4	(Pt100)	0	to 800 °C	D	<u>A8</u>
	0 to 600 °C	Е	A6		-100	to 200 C		C2
14	0.0 to 300.0 °C	1	D3		-200	to 400 C	D	C4
JT	0.0 to 400.0 °C	1	D4		-200	to 600 C		06
	0 to 300 °C	J	A3		-200	to 800 C	DI	C8
J2	0 to 400 °C	J	A4	Input typ		type	Co	de
	0 to 800 °C	J	A8	AN1 0 to 20	)mV		V	01
	0 0 to 300 0 °C	Т	D3	AN2 0 to 50	)mV	-1999 to 9999	V	02
т	0.0 to 400.0 °C	т	D4	AN3 0 to 5\	/DC	-199.9 to 999.9	V	03
S ++	0.0 to 400.0 °C		D4 P6	AN3 0 to 10	DDDC		V	04
D	0 to 1800 °C	<u> </u>	D0	AN4 1 to 5	/DC	-19.99 to 99.99	V	08
R	0 10 1700 C	<u>r</u> x	B/	AN4 2 to 10	DVDC	1 000 to 0 000	V	09
В	200 to 1800 C	<u> </u>	88	AN4 4 to 20	)mA	-1.777 10 9.999	A	03
N Mu2 De25	U to 1300 C		B3	AN3 0 to 20	)mA		Α	02
wu3_Re25	600 to 2000 C	VV	B0	AN3 0 to 10	DmA		A	01

\*\*S type input: 0-100°C range cannot guarantee the accuracy

Note: Clients can set TC, RTD by keyboard ,please set the input type coinide with the sensor. Check details of the manual"6.3" parameter INP1, If need analog signal inputs, please specified when order.(Except 0-20mV or 0-50mV input)



MY06P-616-E1